## **Autonics**

# Two-Degree-of-Freedom PID Temperature Controllers



# **TN Series** PRODUCT MANUAL

# For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

The specifications, dimensions, etc are subject to change without notice for product improvement Some models may be discontinued without notice.

### Features

- · 2-DOF PID algorithm optimized for various control environments
- + 50 ms high-speed sampling and  $\pm 0.2\%$  display accuracy
- · Program control and fixed control models available
- Up to 10 patterns X 20 steps program setting (program control model)
- Timer function for preset operation (fixed control model)
- Simultaneous heating/cooling and automatic/manual control function
- Control functions: Group PID, Zone PID, Anti Reset Windup (ARW)
   Control status monitoring of up to 10 events
- Control status monitoring of up to 10 events
- RS485 communication output model available
- Communication protocols: Modbus RTU/ASCII, PLC ladderless, Sync-Master
- Communication speed: up to 115,200bps
- Heater burnout alarm function (CT input)Parameter setting via PC
- Comprehensive Device Management Software (DAQMaster) provided
- Communication converter connection with front loader port (TNH, TNL only)
- Shortcut key setting with front user key button [U]
- · Easy maintenance with detachable terminal blocks

#### **Safety Considerations**

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- $\Delta$  symbol indicates caution due to special circumstances in which hazards may occur.
- **Warning** Failure to follow instructions may result in serious injury or death
- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.(e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) Failure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use or store the unit in the place where flammable/explosive/ corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.
- Failure to follow this instruction may result in explosion or fire. **03. Install on a device panel to use.**
- Failure to follow this instruction may result in electric shock.04. Do not connect, repair, or inspect the unit while connected to a power source.
- Failure to follow this instruction may result in fire or electric shock. **05. Check 'Connections' before wiring.**
- Failure to follow this instruction may result in fire.
- **06.** Do not disassemble or modify the unit. Failure to follow this instruction may result in fire or electric shock.
- ▲ Caution Failure to follow instructions may result in injury or product damage
- 01. When connecting the power input and relay output, use AWG 20 (0.50 mm<sup>2</sup>) cable or over, and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m.

When connecting the sensor input and communication cable without dedicated cable, use AWG 28 to 16 cable and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m.

Failure to follow this instruction may result in fire or malfunction due to contact failure.

- 02. Use the unit within the rated specifications.
- Failure to follow this instruction may result in fire or product damage 03. Use a dry cloth to clean the unit, and do not use water or organic solvent.
- Failure to follow this instruction may result in fire or electric shock. 04. Keep the product away from metal chip, dust, and wire residue which flow
- into the unit.

Failure to follow this instruction may result in fire or product damage.

#### **Cautions during Use**

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- Check the polarity of the terminals before wiring the temperature sensor. For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length. For thermocouple (TC) temperature sensor, use the designated compensation wire for extending wire.
- Keep away from high voltage lines or power lines to prevent inductive noise. In case
  installing power line and input signal line closely, use line filter or varistor at power line
  and shielded wire at input signal line. Do not use near the equipment which generates
  strong magnetic force or high frequency noise.
- Do not apply excessive power when connecting or disconnecting the connectors of the product.



- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.
- When changing the input sensor, turn off the power first before changing. After changing the input sensor, modify the value of the corresponding parameter.
- Do not overlapping communication line and power line. Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect of external noise.
- Make a required space around the unit for radiation of heat. For accurate temperature measurement, warm up the unit over 20 min after turning on the power.
- Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used.
- This unit may be used in the following environments.
   Indoors (in the environment condition rated in 'Specifications')
- Altitude Max. 2,000 m - Pollution degree 2
- Installation category II

# **Ordering Information**

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website .

T N O - O O O O	6	- 0	8 - 6	)		
● Size S: DIN W 48 × H 48 mm H: DIN W 48 × H 96 mm L: DIN W 96 × H 96 mm	R: Rel S: SSF	<b>ntrol outj</b> ay R drive rrent or SS				
<b>O Control method</b> No mark: Fixed control P: Program control	<b>7 Co</b> N: No R: RS4	ine .	tion			
<b>S Power supply</b> 4: 100 - 240 VAC	③ Terminal type S: Screw					
Alarm outputs	<b>ම</b> Ор	tion inpu	t/output			
2: Alarm 1 / 2 4: Alarm 1 / 2 / 3 / 4	No.	Digital input	CT input	Transmission output		
6: Alarm 1 / 2 / 3 / 4 / 5 / 6	006	0	1	0		
G Control output 1	008	2	1	0		
R: Relay	009	3	1	0		
S: SSR drive	014	0	1	1		
C: Current or SSR drive	031	0	2	1		

#### Manual

For proper use of the product, refer to the manuals and be sure to follow the safety considerations in the manuals.

**035** 6

Download the manuals from the Autonics website.

#### Software

Download the installation file and the manuals from the Autonics website.

#### DAQMaster

DAQMaster is comprehensive device management program. It is available for parameter setting, monitoring.

#### **Product Components**

Product (+ bracket)

Instruction manual

#### **Sold Separately**

- Front cover: FSA / FHA / FLA-COVER
   Current transformer (CT)
- Terminal protection cover: RSA / RMA / RHA / RLA-COVER
- Communication Converter: SCM-USP / SCM-38I / SCM-US48I / SCM-WF48

#### **Specifications** 100 - 240 VAC~, 50/60 Hz Power supply Permissible voltage range 90 to 110 % of rated voltage Power consumption $\leq$ 8 VA **Display type** 11 segment, LCD type (operating value display part: 7 segment) Sampling period 50 / 100 / 250 ms (parameter) Input specification Refer to 'Input Type and Using Range' • 0.0-50.0 A (primary current measurement range) CT • CT ratio: 1/1.000 Measurement accuracy: ±5% F.S. ±1digit Option • Contact - ON: $\leq 2 \text{ k}\Omega$ , OFF: $\geq 90 \text{ k}\Omega$ input • Non contact - residual voltage $\leq 1.0$ V, leakage current $\leq 0.1$ mA Digital • Outflow current: $\approx$ 0.5 mA per input Relay 250 VAC~ 3A 1a Control SSR 12 VDC= $\pm$ 2 V, $\leq$ 20 mA output DC 0 - 20 mA or DC 4 - 20 mA (parameter), Load resistance: $\leq$ Current 500 Ω Alarm 250 VAC~ 3 A 1a Option DC 4 - 20 mA (load resistance: $\leq$ 500 $\Omega$ , output accuracy: $\pm$ 0.3% Transmission output F.S.) Communication RS485 Туре ON/OFF, P, PI, PD, PID Multi S\ $\leq 4 \text{ SV}$ Group PID Control ≤ 8 group type Zone PID 4 zones ARW (Anti Reset 50 to 200 % Windup) Program $\leq$ 10 patterns Program control Step $\leq$ 200 steps (1 pattern: $\leq$ 20 steps) Setting type Time setting • Thermocouple, RTD: 1 to 100 (0.1 to 100.0) °C/°F Hysteresis Analog: 1 to 100 digit Proportional band (P) 0.1 to 999.9 °C (0.1 to 999.9%) Integral time (I) 0 to 9,999 sec Derivative time (D) 0 to 9,999 sec Relay / SSRP output: 0.1 to 120.0 sec Selectable current or SSR drive output: 1.0 to 120.0 sec Control cycle (T) 0.0 to 100.0% Manual reset Between the charging part and the case: **Dielectric strength** 3,000 VAC~ 50/60 Hz for 1 min 0.75 mm amplitude at frequency of 5 to 55 Hz in each X, Y, Z Vibration direction for 2 hours • OUT1/2: ≥ 5,000,000 operations Mechanical AL1/2/3/4/5/6: ≥ 20,000,000 operations Relay life OUT1/2: ≥ 200,000 operations cycle Electrical • AL1/2/3/4/5/6: ≥ 100,000 operations $\geq$ 100 MΩ (500 VDC == megger) Insulation resistance Double insulation or reinforced insulation (mark: , dielectric Insulation type strength between the measuring input part and the power part: 3 kV) $\pm 2\,\text{kV}$ square shaped noise by noise simulator (pulse width: $1\,\mu\text{s})$ Noise immunity R-phase, S-phase Memory retention $\approx$ 10 years (non-volatile semiconductor memory type) Ambient temperature -10 to 50 °C, storage: -20 to 60 °C (no freezing or condensation) Ambient humidity 35 to 85%RH **Protection structure** IP65 (Front panel, IEC standards) • TNS: top side • TNH, TNL: front side Loader port • TNS: ≈ 128 g (≈ 156 g) • TNL: ≈ 301 g (≈ 443 g) • TNH: $\approx$ 184 g ( $\approx$ 286 g) Unit weight (packaged) Certification C E 21% . 🔊 🕼 EAE

### **Communication Interface**

RS485	
Comm. protocol	Modbus RTU/ASCII, Sync-Master, PLC ladderless
Connection type	RS-485, RS-422A
Application standard	EIA RS485 compliance with
Maximum connection	32 units (address: 01 to 99)
Synchronous method	Asynchronous
Comm. Method	Two-wire half duplex
Comm. effective range	≤ 800 m
Comm. speed	$\leq$ 115,200 bps
Response time	5 to 99 ms (default: 20 ms)
Start bit	1 bit (fixed)
Data bit	8 bit (fixed)
Parity bit	None (default), Odd, Even
Stop bit	1 bit, 2 bit (default)
EEPROM life cycle	pprox 1,000,000 operations (Erase / Write)

1 character of ModBus RTU is fixed at 11 bit.

#### Input Type and Using Range

The setting range of some parameters is limited when using the decimal point display.

Input typ	e	Decimal point	Display	Using range (°C)	Using range (°F)
	K (CA)	1	к с Я.Н	-200 to 1,350	-328 to 2,462
	R (CA)	0.1	K E A.L	-199.9 to 999.9	-199.9 to 999.9
	J (IC)	1	JI E.H	-200 to 800	-328 to 1,472
	J (IC)	0.1	JI E.L	-199.9 to 800.0	-199.9 to 999.9
	E (CR)	1	E C R.H	-200 to 800	-328 to 1,472
	E (CR)	0.1	E C R.L	-199.9 to 800.0	-199.9 to 999.9
	T (CC)	1	Е С С.Н	-200 to 400	-328 to 752
	1 (CC)	0.1	E C C.L	-199.9 to 400.0	-199.9 to 752.0
	B (PR)	1	ь PR	0 to 1,800	32 to 3,272
<b>T</b>  =	R (PR)	1	R PR	0 to 1,750	32 to 3,182
Thermo	S (PR)	1	S PR	0 to 1,750	32 to 3,182
-couple	N (NN)	1	N NN	-200 to 1,300	-328 to 2,372
	C (TT) 01)	1	C EE	0 to 2,300	32 to 4,172
	G (TT) 02)	1	ն եե	0 to 2,300	32 to 4,172
	L (IC)	1	LI C.H	-200 to 900	-328 to 1,652
		0.1	LI E.L	-199.9 to 900.0	-199.9 to 999.9
	U (CC)	1	U С С.Н	-200 to 400	-328 to 752
		0.1	UCC.L	-199.9 to 400.0	-199.9 to 752.0
	Platinel II	1	PLII	0 to 1,390	32 to 2,534
	L (RUS)	1	L R.H	-200 to 800	-328 to 1,472
	L (RUS)	0.1	L R.L	-199.9 to 800.0	-199.9 to 999.9
	Cu50 Ω	0.1	CU S	-199.9 to 200.0	-199.9 to 392.0
	Cu100 Ω	0.1	C U 10	-199.9 to 200.0	-199.9 to 392.0
	JPt100 Ω	1	JPE.H	-200 to 650	-328 to 1,202
RTD	JPLIOU 12	0.1	JPE.L	-199.9 to 650.0	-199.9 to 999.9
RID	DPt50 Ω	0.1	dPE5	-199.9 to 600.0	-199.9 to 999.9
	DPt100 Ω	1	dPE.H	-200 to 650	-328 to 1,202
	DPLIOU 12	0.1	dPE.L	-199.9 to 650.0	-199.9 to 999.9
	Nickel120 Ω	1	NI 12	-80 to 260	-112 to 500
	0 to 10 V	-	AV 1	0 to	10 V
	0 to 5 V	-	Ar 2	0 to	5 V
Analag	1 to 5 V	-	AV 3	1 to	5 V
Analog	0 to 100 mV	-	AMV I		100 mV
	0 to 20 mA	-	AMA I	0 to	20 mA
	4 to 20 mA	-	8882	4 to	20 mA

• Permissible line resistance per line:  $\leq 5 \Omega$ 

01) C (TT): Same as existing W5 (TT) type sensor

02) G (TT): Same as existing W (TT) type sensor

#### Display accuracy

Input type	Using temperature	Display accuracy
Thermo -couple RTD	At room temperature (23°C ±5 °C)	$\begin{array}{l} (\text{PV}\pm0.2\% \mbox{ or }\pm1\ ^\circ\mbox{C higher one)}\pm1\mbox{-digit}\\ \bullet\ \text{Thermocouple K, J, T, N, E below-100\ ^\circ\mbox{ cand L, U, PLII,}\\ RTD Cu50\ \Omega, DPt50\ \Omega; (\text{PV}\pm0.3\% \mbox{ or }\pm2\ ^\circ\mbox{C higher one)}\\ \pm1\mbox{-digit}\\ \bullet\ \text{Thermocouple C, G and R, S below 200\ ^\circ\mbox{C:}}\\ (\text{PV}\pm0.3\% \mbox{ or }\pm3\ ^\circ\mbox{C higher one)}\\ \pm1\mbox{-digit}\\ \bullet\ \text{Thermocouple B below 400\ ^\circ\mbox{C: There is no accuracy}}\\ \text{standards}\end{array}$
RID	Out of room temperature range	$\begin{array}{l} (\text{PV}\pm0.5\% \text{ or }\pm2\ ^\circ\text{C} \text{ higher one})\pm1\text{-digit}\\ \cdot\text{RTD} Cu50\ \Omega,\ \text{DPt50}\ \Omega:\ (\text{PV}\pm0.5\% \text{ or }\pm3\ ^\circ\text{C} \text{ higher one})\\ \pm1\text{-digit}\\ \cdot\text{Thermocouple R, S, B, C, G:}\\ (\text{PV}\pm0.5\% \text{ or }\pm5\ ^\circ\text{C} \text{ higher one})\pm1\text{-digit}\\ \cdot\text{Other sensors:}\leq\pm5\ ^\circ\text{C}(\leq-100\ ^\circ\text{C})\end{array}$
Analog	At room temperature (23°C ±5 °C)	±0.2% F.S. ±1-digit
Analog	Out of room temperature range	±0.5% F.S. ±1-digit

# **Unit Descriptions**

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Display Name

Display Name

Lock

Wait

alarm

6. Output status indicator

Control

output

Manual

control

Control

Program

Alarm output

output stop

control hold

Auto tuning

Program

Heater break

LOCK

PROG

WAIT

HBA1/2

OUT1/2

AT

MAN

STOP

HOLD

5

• Below is based on TNL Series.

1

2

3

Description

control.

Description

is ON

sec

mode

is ON

stop mode

is hold status

Turns ON during key lock status

Turns ON during waiting status.

Turns ON when the control output

Flashes during auto tuning every 1

Turns ON during manual control

Turns ON during control output

Turns ON when program control

Turns ON when the alarm output

Turns ON during program

Turns ON when the heater

break alarm output is ON.

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5. Operation status indicator

• The shape and function of each part may be different depending on the series, and it is possible to check the additional information in the user manual.

#### 1. PV display part (White)

RUN mode: Displays PV (Present value) and unit.
 Setting mode: Displays parameter name

# 2. SV display part (Green)

RUN mode: Displays SV (Setting value) and unit.
Setting mode: Displays parameter setting value.
3. Operating value display part (Yellow)

 RUN mode: Displays selected value among MV (Manipulated output value), P/S, TM, CT with unit.

#### 4. Temperature control indicator

 Fixed control: Relative PV value status display based on SV

 $PV > SV (\nearrow), PV = SV (\rightarrow), PV < SV (\searrow)$ 

Program control: Displays temperature control status of up (↗), hold (→), down (↘).

_	7. Input key	
	Display	Name
-	[U]	User key
	[M]	Mode key
_	[◀], [▼], [▲]	Setting value
	[◀], [♥], [▲]	control key

#### 8. PC loader port

For connecting communication converter (SCM-USP).

# Errors

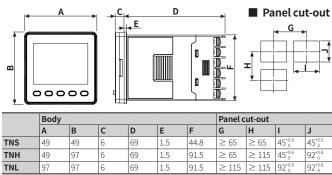
AL1 to 6

Display	Input	Description	Output	Troubleshooting		
oPEN	Temperature sensor	Flashes at 0.5 sec interval when input sensor is disconnected or sensor is not connected.	'Sensor error, MV' parameter setting value	Check input sensor status.		
0, 5,4	Analog	Flashes at 0.5 sec interval when input is over F.S. $\pm 10\%$ .	'Sensor error, MV' parameter setting value	Check analog input status.		
нннн	Temperature sensor	Flashes at 0.5 sec interval if the input value is above the input range. $^{(1)}$	Heating: 0%, Cooling: 100%			
пппп	Analog	Flashes at 0.5 sec interval if the input value is over 5 to 10% of high limit or low limit value.	Normal output	When input is within the rated		
LLLL	Temperature sensor	Flashes at 0.5 sec. interval if the input value is below the input range. <sup>01</sup>	Heating: 100%, Cooling: 0%			
LLLL	Analog	Flashes at 0.5 sec interval if the input value is over 5 to 10% of low limit or high limit value.	Normal output			
ERR	-	Flashes at 0.5 sec interval if there is error for setting and it returns to the error-before screen.	-	Check setting method.		
ĿMR.E	-	Flashes twice and stops operation at the start of operation if the timer operation related parameter setting is not completed.	'STOP, MV' parameter setting value	Set the timer operation related parameters.		
P E N.E	-	Flashes twice and stops operation at the start of operation if the program operation related parameter setting is not completed.	'STOP, MV' parameter setting value	Set the program operation related parameters.		
E R.□□	-	Flashes twice the address of failed Slave when using Sync communication or PLC setting copy function.	-	Check the failed slave connection status and communication settings.		

01) Be careful that when HHHH / L L L L error occurs, the control output may occur by recognizing the maximum or minimum input depending on the control type.

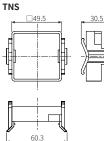
# **Dimensions**

- Unit: mm, For the detailed drawings, follow the Autonics website.
- Below is based on TNS Series.



INS	49	49	6	69	1.5	44.8	$\geq 65$	$\geq 65$	45.0	45 0
TNH	49	97	6	69	1.5	91.5	$\geq 65$	$\geq 115$	45 <sup>+0.6</sup>	92 <sup>+0.8</sup>
TNL	97	97	6	69	1.5	91.5	$\geq 115$	$\geq$ 115	92 <sup>+0.8</sup>	92 <sup>+0.8</sup>

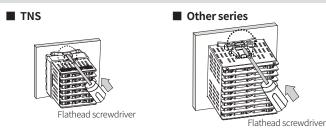
### Bracket







# **Installation Method**

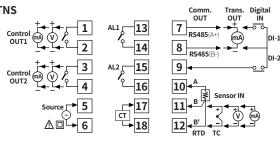


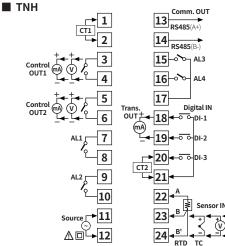
Insert the unit into a panel, fasten the bracket by pushing with tools with a flathead screwdriver.

# Connections

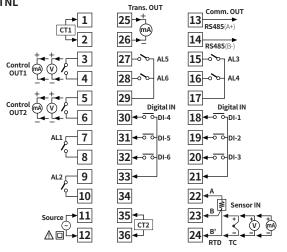
• Digital input is not electrically insulated from internal circuits, so it should be insulated when connecting other circuits.

# TNS





TNL



# **Crimp Terminal Specifications**

• Unit: mm, Use the crimp terminal of follow shape.

≤5.8 ≥3.0

≥3.0 ≤5.8

Fork crimp terminal

Round crimp terminal

### **Initial Display When Power is ON**

When power is supplied, after all display will flash for 1 sec, model name is displayed sequentially. After input sensor type will flash twice, enter into RUN mode.

Display part	1. Model	2. Model	3. Input specification	4. RUN mode
PV & E N 5.P		RS	ЕЧРЕ	oPEN
SV	42RR	006	K E A.H	٥

# **Mode Setting**

$\frown$								
$\left[ \right]$	Auto before			Password	Key input	Entering n	node	
	entering to mode		Deservered in part	Pass	Auto	Selected mode		
	(when using	7	Password input	r-1	[◀], [▲], [▼]	Password	input	
	password)			Fail	[MODE]	Run mode	2	
	[◀], [▲], [▼] (in manual control)	→	MV setting	Move digits Change val Save: Whe Return: [M input over				
	[◀], [▲], [▼] (in auto control)	→	SV setting	Move digits Change val Save and I no key inp	E] or			
RUN	[ <b>▼</b> ] + [ <b>▲</b> ] 3 sec	$\rightarrow$	Control output run/stop	Auto		$\rightarrow$		
KUN	[M] + [ <b>▲</b> ]	$\rightarrow$	Operating value display part (MV / P/S / TM / CT) setting	Auto		$\rightarrow$	RUN	
	[U] + [◀] / [▼] / [▲] 2 sec	$\rightarrow$	Shortcut key 1/2/3	Auto		$\rightarrow$		
	[ <b>◀</b> ] + [ <b>▼</b> ] 3 sec	$\rightarrow$	Key lock ON/OFF	Auto		$\rightarrow$		
	[M] 2 sec	$\rightarrow$	Parameter group	[ <b>◀</b> ] 2 sec		$\rightarrow$		
	[U] 2 sec	$\rightarrow$	U key enter parameter group	[ <b>◀</b> ] 2 sec		$\rightarrow$		
	[ <b>◀</b> ] + [ <b>▲</b> ] + [ <b>▼</b> ] 5 sec	$\rightarrow$	Parameter reset	Refer to 'P	arameter Rese	et' →		

• TNS series does not support 'MV setting', 'Operation value display part setting' mode. For the details, refer to the user manual.

#### **Parameter Reset**

- 01. Press the [◀] + [▲] + [▼] keys for over 5 sec. in run mode, INIT turns ON.
- 02. Change the setting value as YES by pressing the  $[\blacktriangle]$  ,  $[\blacktriangledown]$  keys.
- 03. Press the [M] key to reset all parameter values as default and to return to run mode.

# Function: Alarm

Alarm output sets alarm operation and alarm option. Each alarm operates individually in two alarm output models. When the current temperature is out of alarm range, alarm clears automatically.

	peration				H: Alarm output hysteres				
Mode	Name	Alarm o	peration		Description				
oFF	-	-			No alarm output				
d¥€€	Deviation high limit	OFF SV 100°	H ON PV c 110°C	OFF H ON PV SV 90°C 100°C	If deviation between P and SV as high-limit is higher than set value o deviation temperature the alarm output will b				
		High devia	ation: Set as 10°C	High deviation: Set as -10°C	ON.				
234V	Deviation low limit	ON	/ SV C 100°C	ON H OFF	If deviation between P and SV as low limit is higher than set value o deviation temperature the alarm output will b				
		Low devia	ition: Set as 10°C	Low deviation: Set as -10°C	ON.				
] d V C	Deviation high, low limit		A PV S 90°C 10	IFF H ON V PV °C 110°C ation: Set as 10°C	If deviation between PV and SV as high/lov limit is higher than set value of deviation temperature, the alar output will be ON.				
			Fight, LOW Gevi	auon. Set as 10 C	If deviation between				
[]	Deviation high, low limit	OFF	► H C A PV 90°C 10	PV and SV is higher than the lower limit deviation set value an less than the upper					
	reverse		High, Low devi	ation: Set as 10°C	limit deviation set value, the alarm outpu will be ON.				
PVCC	Absolute value high limit	OFF H	v sv	OFF H ON SV PV 100°C 110°C Absolute value: Set as 110°C	If PV is higher than th absolute value, the output will be ON.				
פרנ	Absolute value low limit	ON P\ 90°	H OFF / SV C 100°C	ON ↑H OFF SV PV 100°C 110°C	If PV is lower than the absolute value, the output will be ON.				
		Absolute	value: Set as 90°C	Absolute value: Set as 110°C					
Mode	Name		Description						
ЬЯ	Loop breal	k alarm	Loop break d	etection, alarm output tur	ms ON.				
56A	Sensor bre	ak alarm	Sensor break	detection, alarm output t	urns ON.				
нья і	Heater bre	ak alarm	At CT1, heate	r break detection, alarm o	utput turns ON.				
ньяг	Heater bre	ak alarm	At CT2, heate	r break detection, alarm o	utput turns ON.				
RUN	Control ou	tput ON	Control outpu	ut ON, alarm output turns	ON.				
Stop	Control ou			ut OFF, alarm output turns					
PRUS	Control ou PAUSE			It PAUSE, alarm output tu					
P.5 Ł	Pattern cor	ntrol start	Pattern contro case of repea	ol start, alarm output turn t start.	s ON. It is also output ir				
P.E N d	Pattern cor	ntrol end	Pattern contro	ol end, alarm output turns	S ON.				
P.o E	Pattern cor delay poin			eration time of the patter ON at the time of exceeding					
5.5 E	Step start i	notice	Step start, ala	rm output turns ON.					
	Chain and in	otico	Stop and ala	ep end, alarm output turns ON.					
5.E N d	Step end n	ouce	Step enu, atai	the step operation time is exceeded, the alarm output turns N at the time of exceeding.					

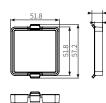
# Option

	ption			
Mode	Name	Description	Condition of reapply	
AL-A	Standard alarm	If it is an alarm condition, alarm output is ON. If it is a clear alarm condition, alarm output is OFF.	-	
AL-P	Alarm latch	If it is an alarm condition, alarm output is ON and maintains ON status.	-	
AL-C	Standby sequence 1	First alarm condition is ignored and from second alarm condition, standard alarm operates. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, standard alarm operates.	Power ON	
AL-d	Alarm latch and standby sequence 1	If it is an alarm condition, it operates both alarm latch and standby sequence. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second 1alarm condition, alarm latch operates.	Power ON	
AL-E	Standby sequence 2	First alarm condition is ignored and from second alarm condition, standard alarm operates. When re- applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, standard alarm operates.	Power ON, change SV, change alarm	
AL-F	Alarm latch and standby sequence 2	Basic operation is same as alarm latch and standby sequence1. It operates not only by power ON/OFF, but also alarm set value, or alarm option changing. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, alarm latch operates.	temperature / operation or change STOP to RUN mode	

# Sold Separately: Front Cover

• Unit: mm

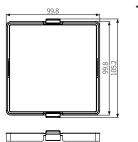
#### TNS: FSA-COVER



# TNH: FHA-COVER



# TNL: FLA-COVER





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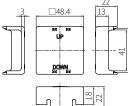
# Sold Separately: Terminal Protection Cover

• Unit: mm

3.8

5

# RSA-COVER: DIN W48 $\times$ H48



RHA-COVER: DIN W48 × H96

91.5

8

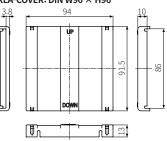
47.2

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# 68.5 (The ,¶ ∷ 1

RMA-COVER: DIN W72  $\times$  H72 70

RLA-COVER: DIN W96 × H96

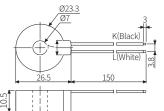


7

#### Sold Separately: Current Transformer (CT)

- Unit: mm
- The current for above CTs is 50A same but inner hole sizes are different. Please use this for your environment. • Do not supply primary current in case that CT output is open. High voltage will be
- generated in CT output.

### CSTC-E80LN



• Max. load current: 80A (50/60Hz)

• Current ratio: 1/1000• Wire wounded resistance:  $31\Omega \pm 10\%$ 

Ø37.1

Ø13

- Wire wounded resistance:  $20\Omega\pm10\%$ 

150

10.8

Current ratio: 1/1000

(F)

40.2

31

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• Wire wounded resistance  $31\Omega \pm 10\%$ 

• Max. load current: 80A (50/60Hz)

CSTS-E80PP

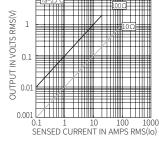
0.5

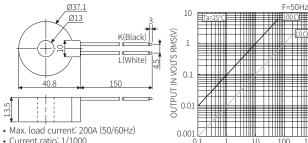
Ø6

<u>Ø3.</u>4

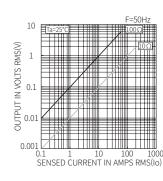
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#### CSTC-E200LN





1000 SENSED CURRENT IN AMPS RMS(Io)



# Segment Table

Current ratio: 1/1000

The segments displayed on the product indicate the following meanings. It may differ depending on the product.

7 S	7 Segment			11	Seg	mer	nt	12 Segment				16 Segment			
٥	0	1	1	٥	0	1	1	٥	0	1	1	٥	0	I	1
1	1	J	J	1	1	J	J	1	1	J	J	1	1	Ū	J
2	2	Ľ	К	2	2	ĸ	К	2	2	К	К	2	2	к	К
Э	3	L	L	Э	3	L	L	Э	3	L	L	Э	3	L	L
ч	4	ñ	М	ч	4	М	М	Ч	4	Μ	М	Ч	4	Μ	М
5	5	n	N	5	5	N	Ν	5	5	N	N	5	5	N	Ν
Б	6	ο	0	6	6	٥	0	Б	6	ο	0	6	6	۵	0
7	7	Ρ	Ρ	Л	7	Ρ	Р	7	7	Ρ	Р	Л	7	Ρ	Ρ
8	8	9	Q	8	8	۵	Q	8	8	۵	Q	8	8	Q	Q
9	9	r	R	9	9	R	R	9	9	R	R	9	9	R	R
R	А	5	S	R	А	5	S	R	Α	5	S	R	A	5	S
ь	В	F	Т	Ь	В	F	Т	Ь	В	F	Т	3	В	T	Т
C	С	U	U	٢	С	U	U	٢	С	U	U	Ľ	С	U	U
d	D	U	V	d	D	V	V	d	D	V	V	IJ	D	$V_{-}$	V
Ε	E	Ļ	W	Ε	Е	М	W	Ε	E	М	W	Ε	E	И	W
F	F	5	Х	F	F	×	Х	F	F	×	Х	F	F	×	Х
G	G	У	Υ	G	G	Ч	Y	6	G	Ч	Y	6	G	ř	Υ
н	Н	Ξ	Ζ	Н	Н	Z	Ζ	Н	Н	Z	Ζ	Н	Н	2	Ζ